



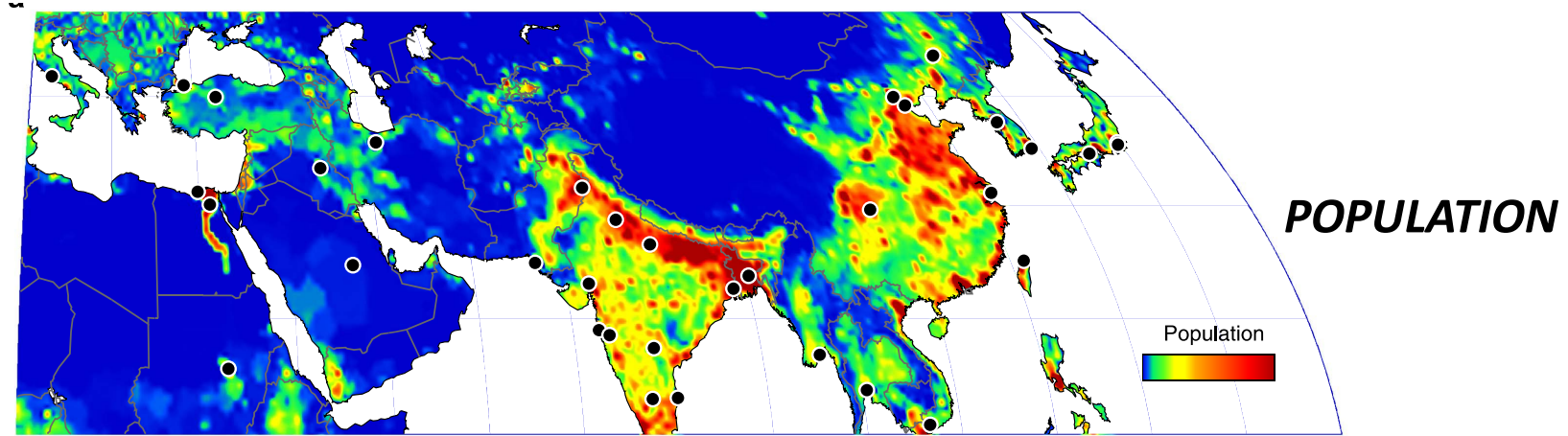
Estimates of Seismic Moment Accumulation Rate from Geodesy

Katherine Guns, David Sandwell, Xiaohua Xu, Yehuda Bock, Lauren Ward, & Bridget Smith-Konter

Outline

- Two methods of calculating moment accumulation rate from geodesy
 - fault-based modeling
 - strain rate-based modeling
- What is the Kostrov layer and how thick is it?
- What is the ratio of off-fault moment accumulation rate to on-fault moment accumulation rate?
- How can InSAR be used to resolve spatial variations in moment accumulation rate?

Large continental earthquakes mainly occur where strain rate exceeds 50 nanostrain/yr



POPULATION

MAGNITUDE

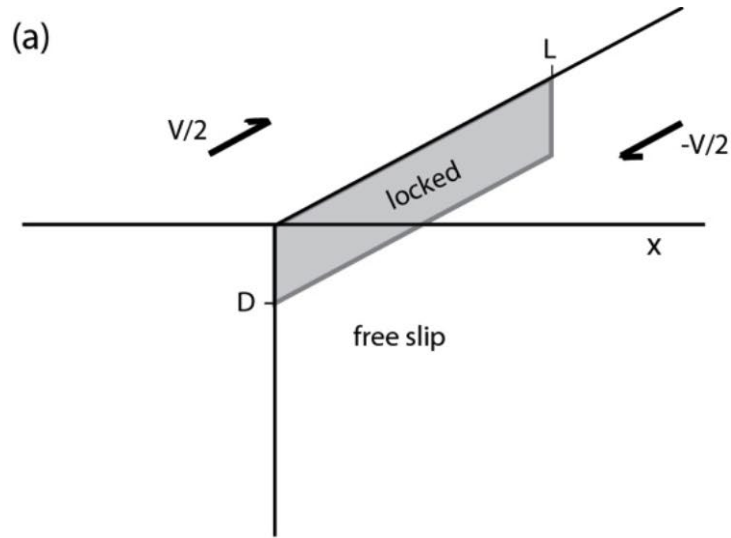
STRAIN

[Elliot et al., 2016]

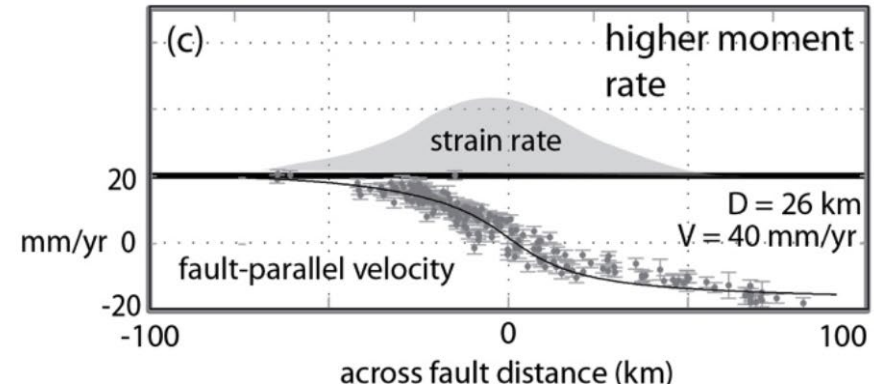
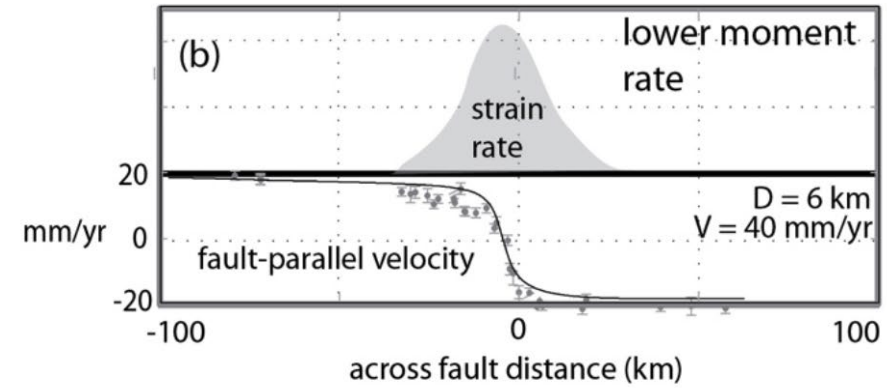
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Approach #1 - Fault-based models

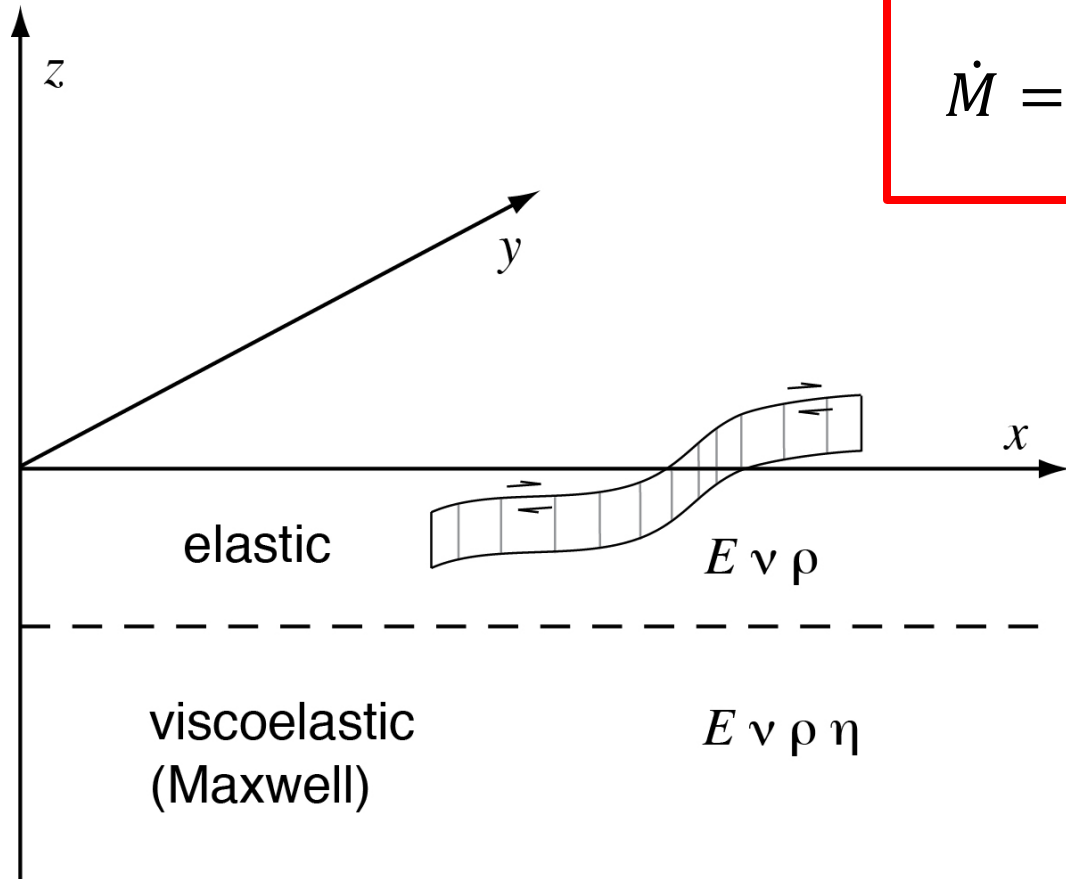


$$\frac{\dot{M}}{L} = \mu V D$$



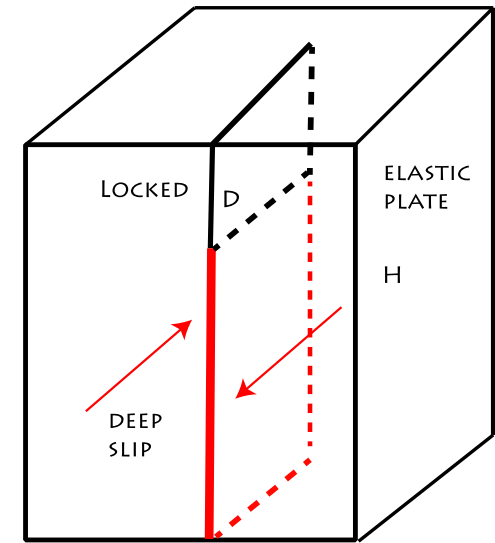
earthquake potential = moment rate \times accumulation time \times rupture length

Fault-based models

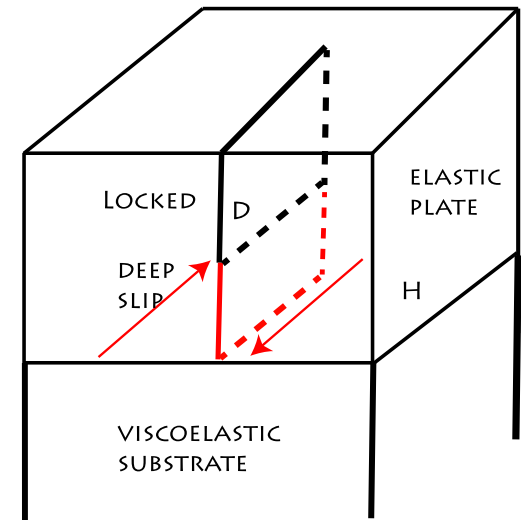


$$\dot{M} = \mu \sum_{i=1}^N V_i D_i L_i$$

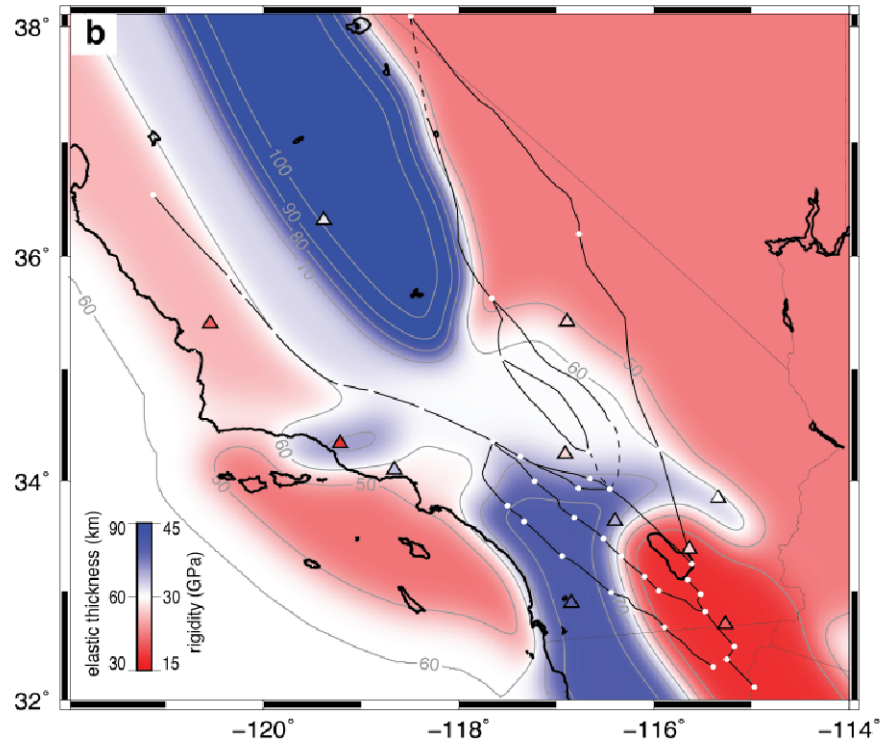
elastic half space



layered half space

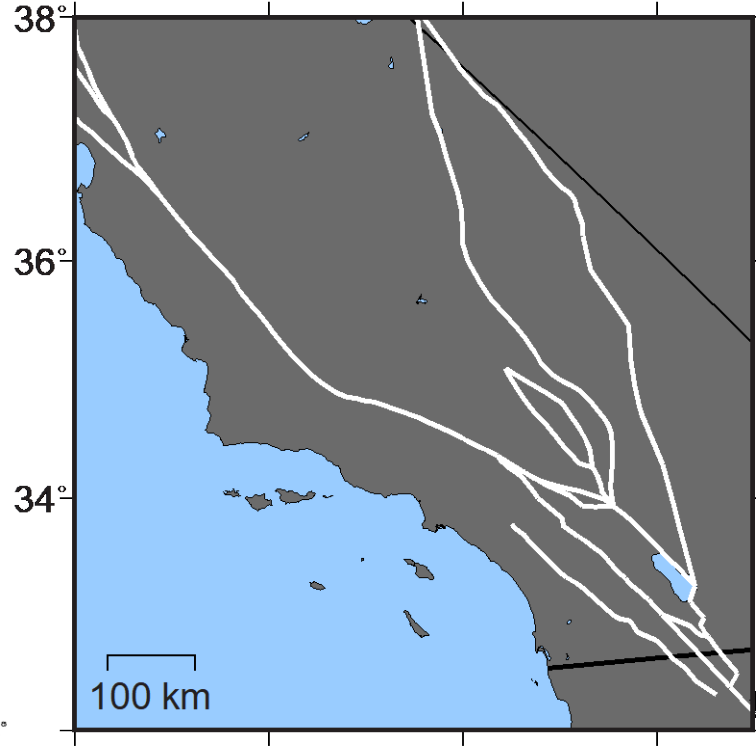


Fault-based models



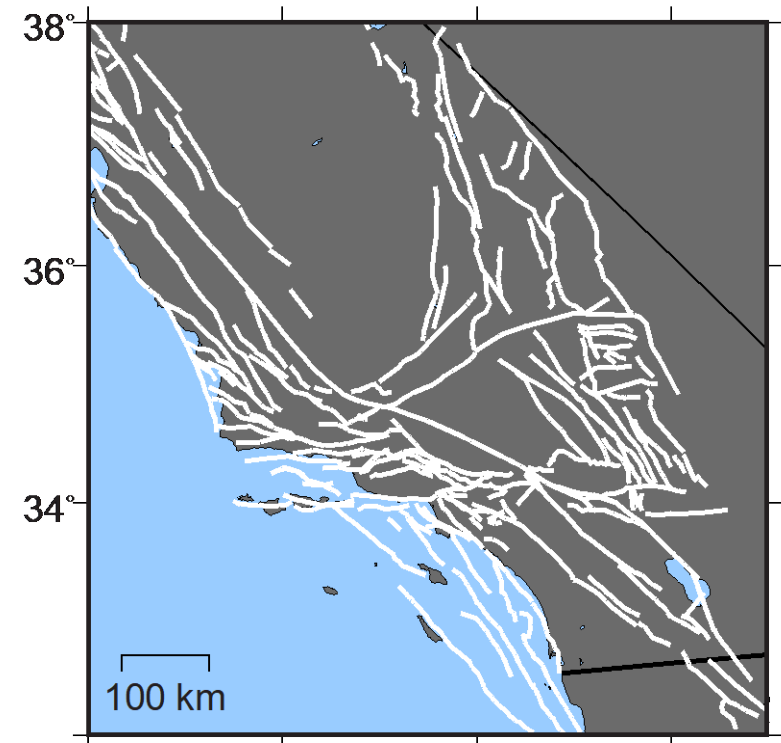
1.20×10^{19} Nm/yr
variable rigidity
layered viscoelastic

Ward et al. (2021)



1.52×10^{19} Nm/yr
uniform rigidity
layered viscoelastic

Zeng & Shen (2016)



1.18×10^{19} Nm/yr
uniform rigidity
elastic half space

Approach #2 - Strain-rate based models

$$\dot{M} = 2\mu HA \begin{bmatrix} \varepsilon_1 & 0 & 0 \\ 0 & \varepsilon_2 & 0 \\ 0 & 0 & -\Delta \end{bmatrix}$$

Three, commonly used ways to reduce tensor moment to scalar moment.

$$M_o^W = 2 * \mu HA \max(|\varepsilon_1|, |\varepsilon_2|)$$

$$M_o^{WG} = \mu HA (\varepsilon_1 - \varepsilon_2)$$

$$M_o^{SS} = 2 * \mu HA \max(|\varepsilon_1|, |\varepsilon_2|, |\Delta|)$$

[Savage and Simpson, 1997]

deduce the components of the moment-rate tensor \dot{M} within the vertical prism defined by the surface area A at a seismicogenic thickness H (Fig. 1). The free-surface boundary conditions imply that $\varepsilon_{23} = \varepsilon_{32} = 0$ and $\varepsilon_{13} = \varepsilon_{31} = 0$, an

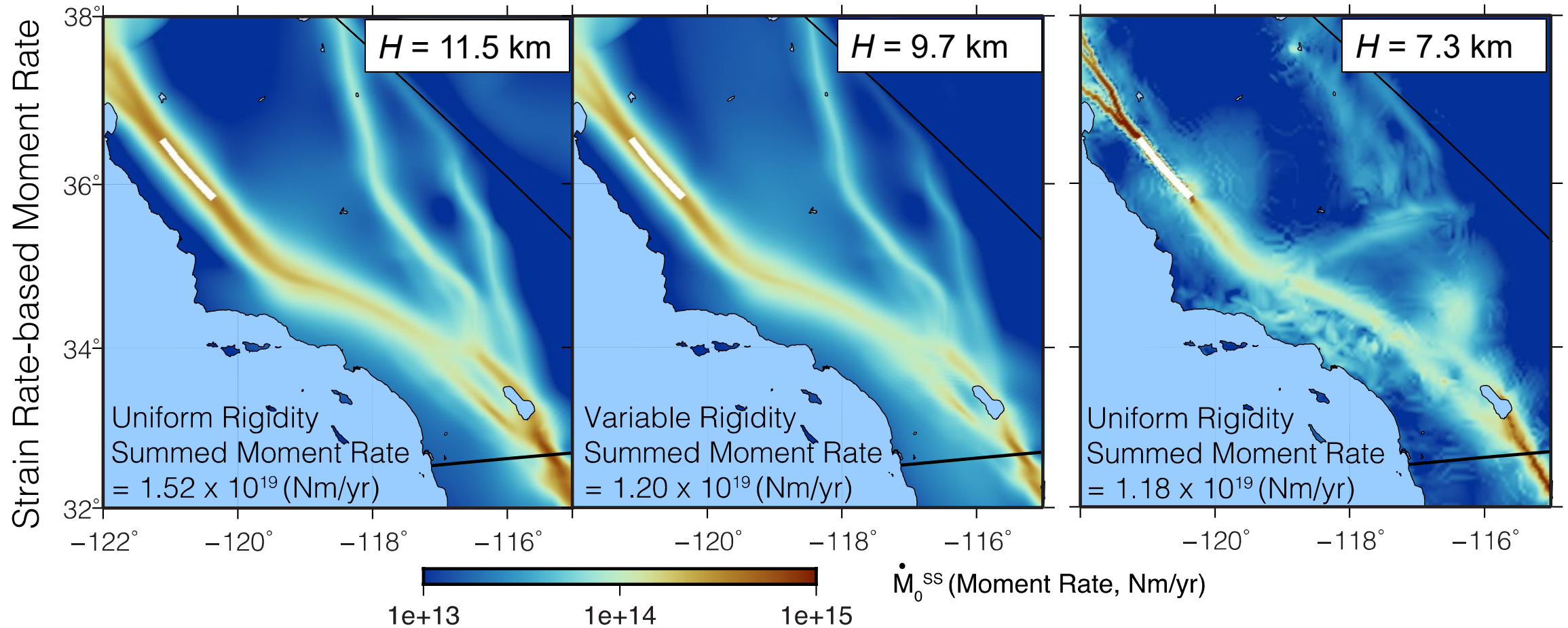
$$M_{ij} = 2\mu HA \varepsilon_{ij}$$

ap the accumulation of seismic moment. One critical assumption in Ward's formulation is that the average strain over the seismicogenic volume (thickness H) could be placed by the average strain rate measured at the surface and then used the Kostrov formula

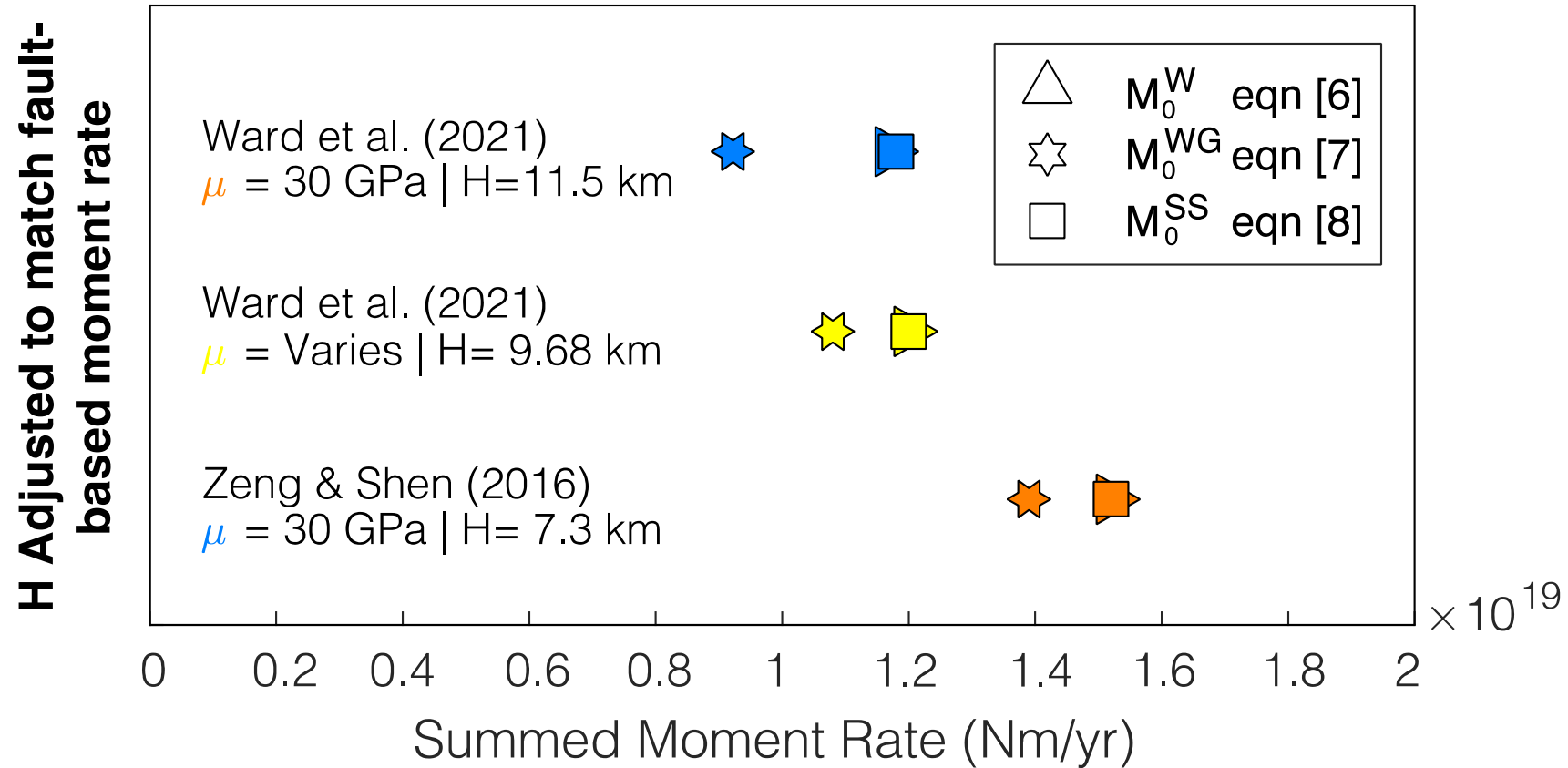
The Kostrov thickness H is equal to the seismicogenic thickness on a fault but could be different away from a fault and varies from fault to fault. Moreover, the shear modulus varies spatially so H is simply an unknown parameter [Ward 1994]

Strain-rate based models

The Kostrov thickness H is adjusted so the strain-rate based and fault-based moments match.

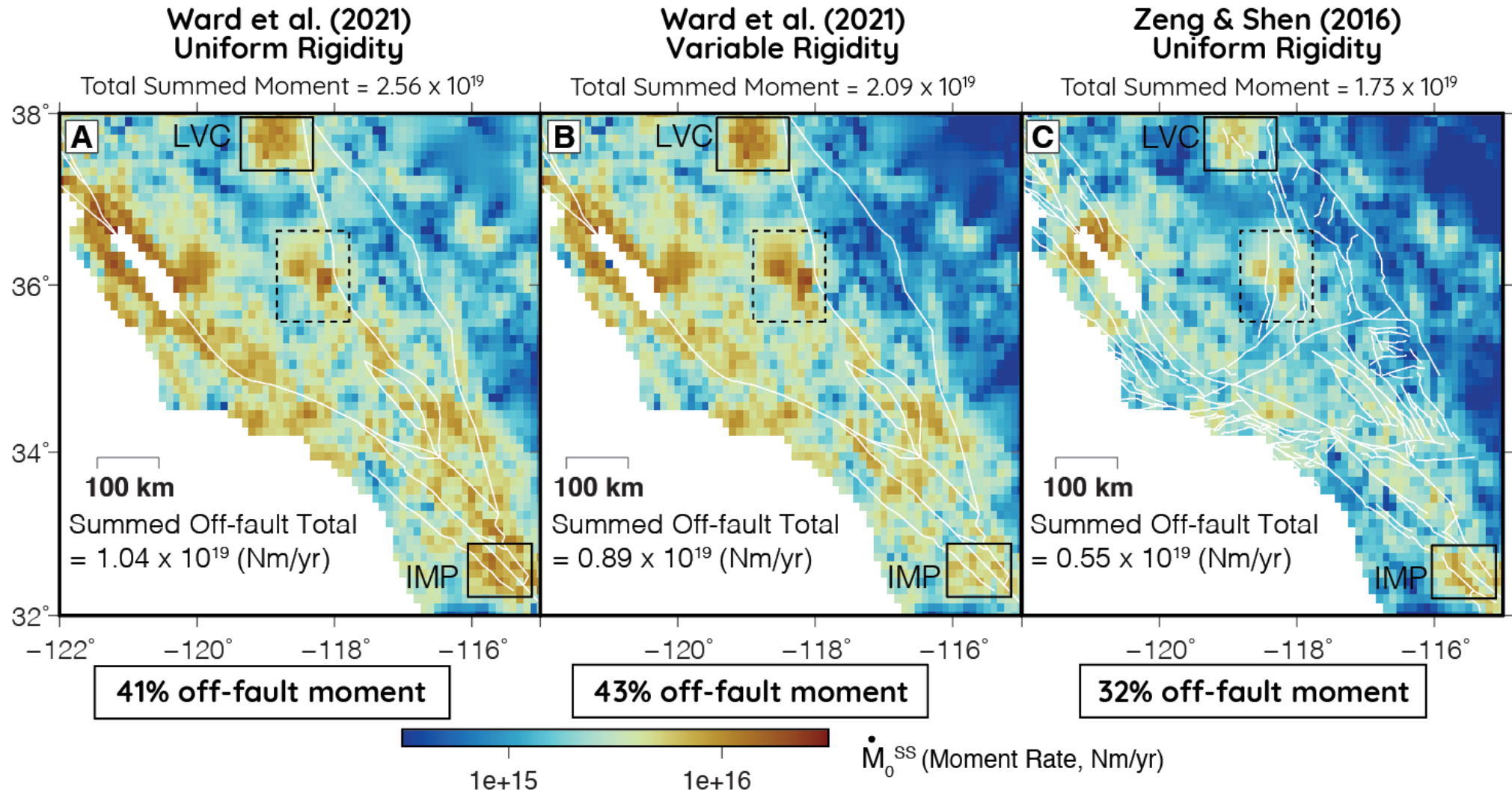


Bounds on Kostrov thickness

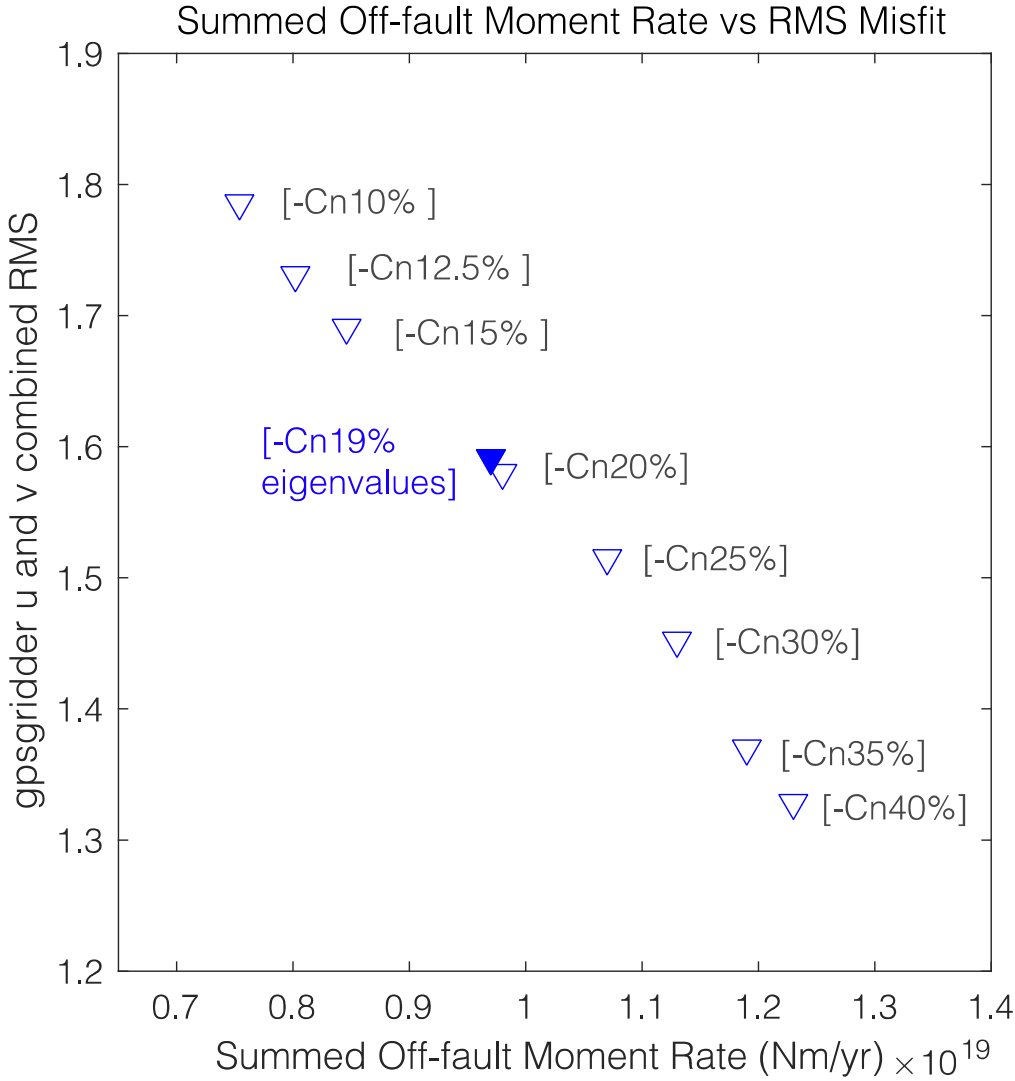


7.3 to 11.5 km < seismogenic thickness of 11 to 20 km

Off-fault moment accumulation rate

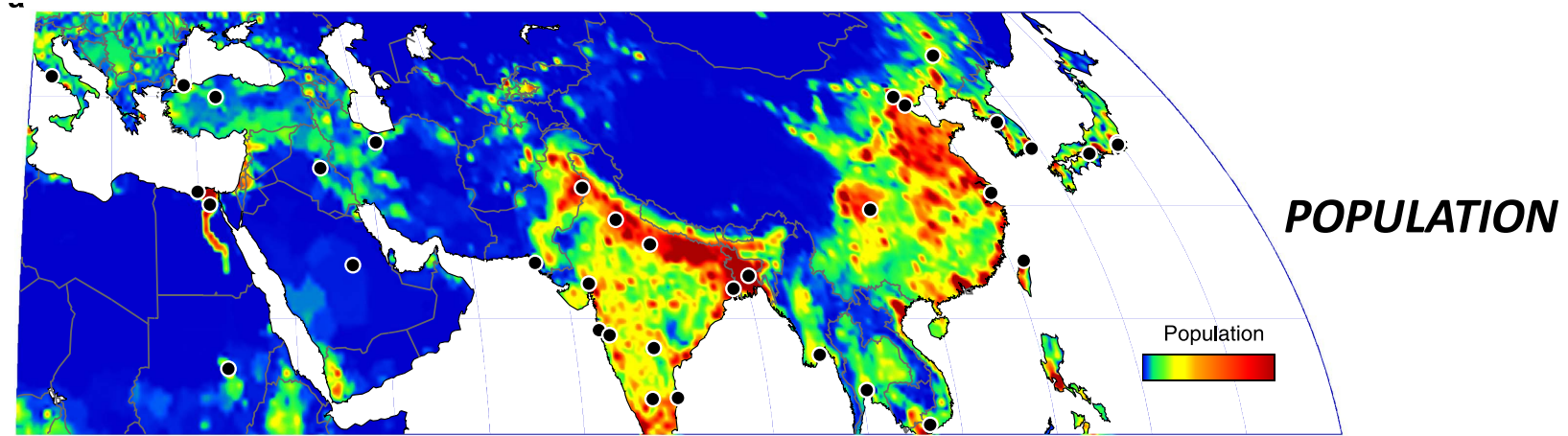


Uncertainty in off-fault moment accumulation rate due to gridding method/parameters [e.g., Maurer and Materna, 2023]



Uncertainty due to gridding method ~ 17%

Large continental earthquakes mainly occur where strain rate exceeds 50 nanostrain/yr

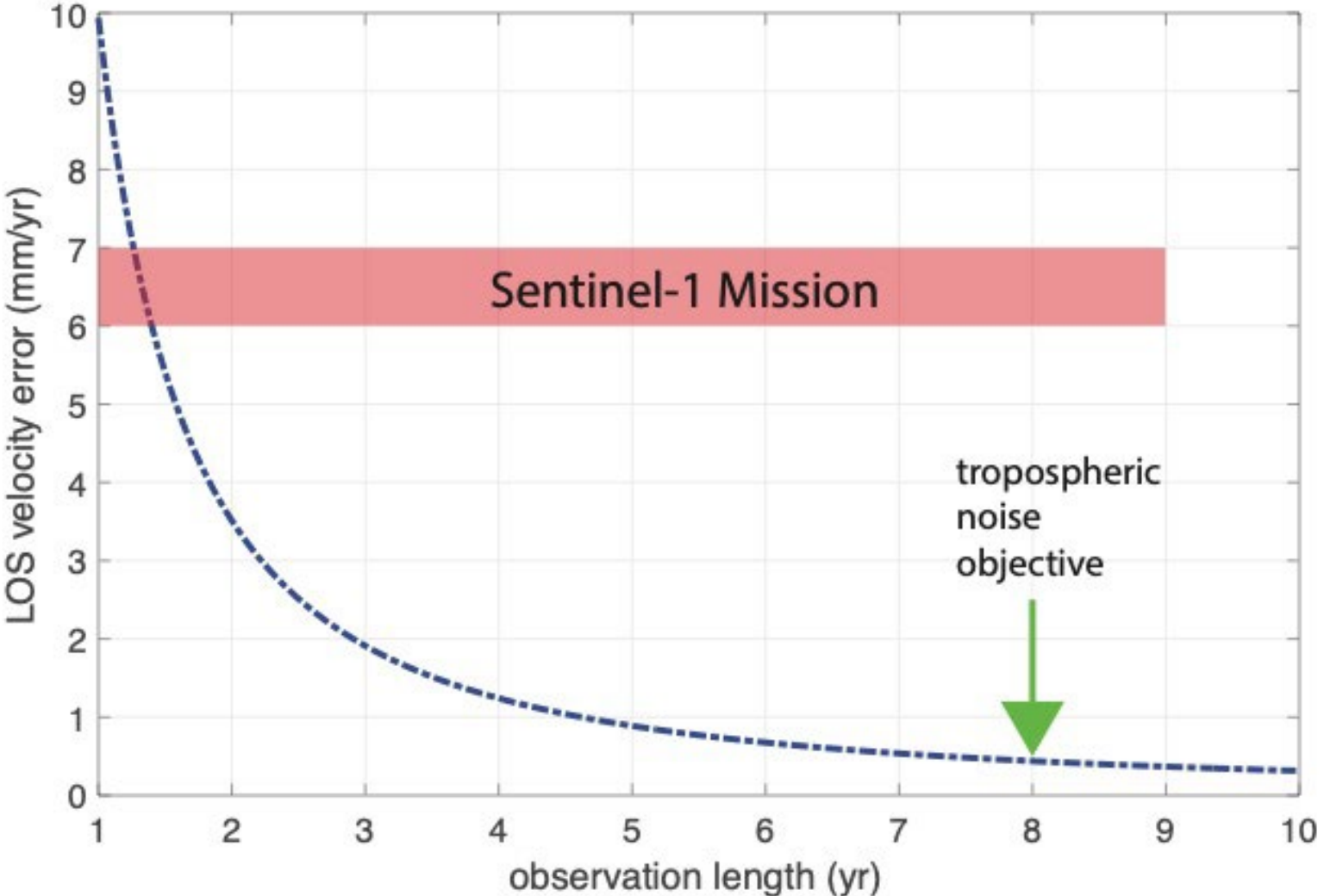


MAGNITUDE

STRAIN

[Elliot et al., 2016]

InSAR can improve the accuracy of this interpolation.



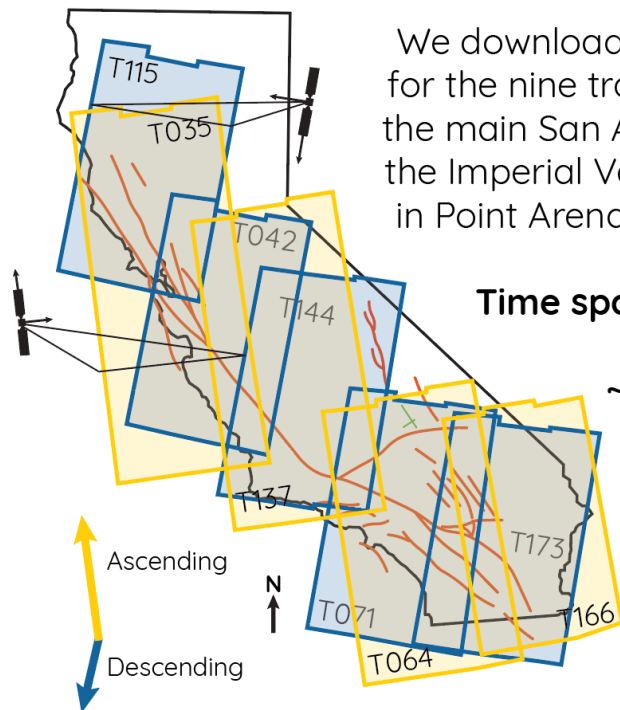
Most destructive earthquakes occur in regions where the tectonic strain rate exceeds 50 nanostrain/yr . This corresponds to an average velocity accuracy of 0.5 mm/yr over the 10 km averaging distance. [Elliott et al., 2016]

[Emardson et al., 2003]

Improve strain rate accuracy with GNSS and InSAR

[Guns et al., in prep.]

Data



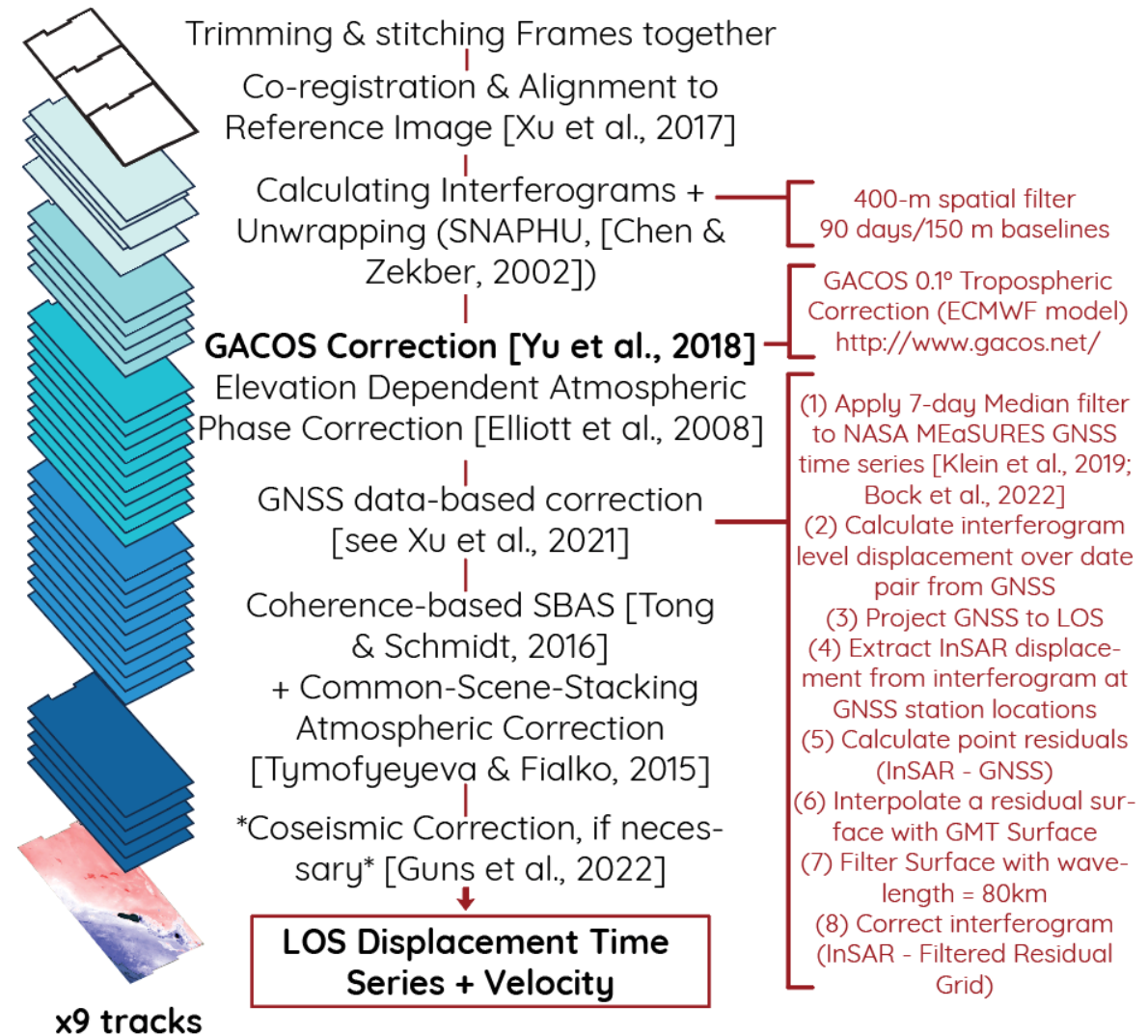
We download ESA Sentinel-1A/B SAR data for the nine tracks in California that cover the main San Andreas plate boundary from the Imperial Valley to the northern extent in Point Arena, CA.

Time span: 2014.8500 – 2022.0

~2300+ Level 1 Single Look Complex Files

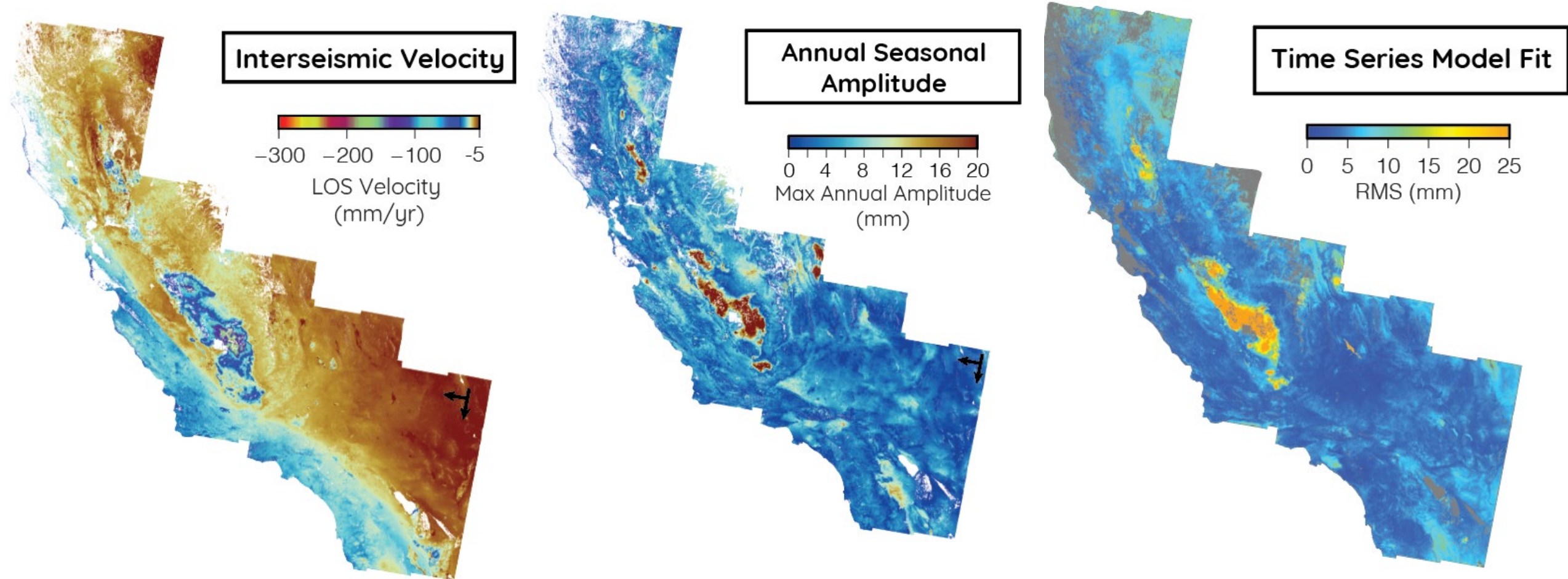
Figure 1. Approximate data coverage extents in our analysis for nine Sentinel-1 SAR satellite tracks over the faults of the San Andreas Plate boundary (red lines).

Methods

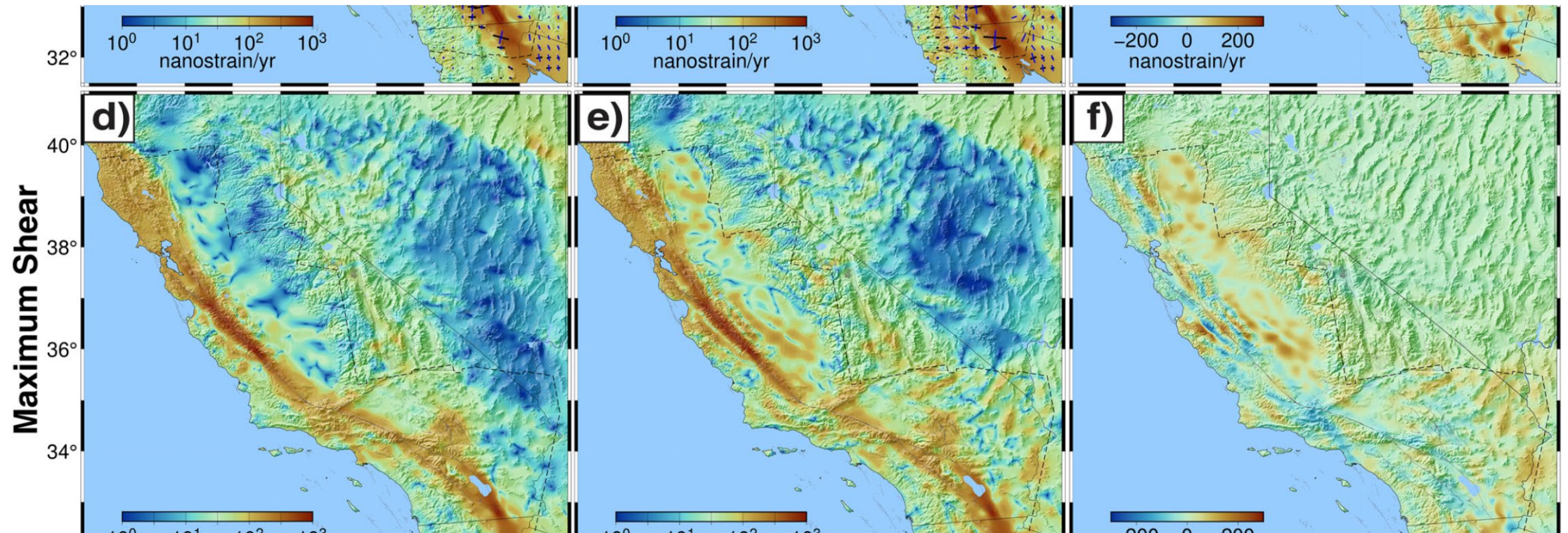


Time Series Trajectory Model

$$D(t) = \underbrace{V(t)}_{\text{Interseismic velocity}} + \underbrace{A\sin(2\pi t) + B\cos(2\pi t)}_{\text{Annual Seasonal}} + \underbrace{C\sin(4\pi t) + D\cos(4\pi t)}_{\text{Semi-Annual Seasonal}} + \underbrace{D_{\text{eq}} * H(t)}_{\text{Coseismic}} + \underbrace{D_{\text{eq|exp}}(1 - e^{-\frac{\Delta t}{\tau}}) * H(t) + D_{\text{eq|log}}(\log(1 + \frac{\Delta t}{\tau})) * H(t)}_{\text{Postseismic}}$$



InSAR can improve the accuracy of this interpolation.



[Xu et al., 2021]

Strain rate based on 4.5 years of Sentinel-1 data have errors > 100 nanostrain/yr. **This is currently being revised with 3 more years of data.**

Conclusions

- Three earthquake cycle models are used to estimate:
 - Kostrov thickness of 11.5, 9.7 and 7.3 km
 - off-fault moment rates of 41%, 43% and 32%
- The model with variable crustal rigidity has 21% lower moment rate
- The model having more faults has a lower off-fault moment rate.
- The largest uncertainty (17%) in calculating moment rate from strain rate is the amount of smoothing used to grid the GNSS velocity data.
- Combined InSAR/GNSS velocity estimation should reduce this interpolation error.

Geodetic moment accumulation rate versus Seismic moment release rate

